

Name - MD. Rakib Hasan.

ID - 2216080021

Course Name/code - Digital Electronics And pulse Technique

Code - CSE-223.

Answer to the question- 1-(a)

① Ans: Flip-flop: A flip-flop in digital electronics is a circuit with two stable states that can be used to store binary data.

The stored data can be changed by applying varying inputs.

Flip-flop and latches are fundamental building blocks of

Digital Electronics system used in computers, communication, and

many other types of systems. Both are used as data storage

elements.

For Example: Let us talk about SR latch and SR flip

flop. In this circuit when you set S as active.

The output Q will be high and \bar{Q} will be low.

This is irrespective of anything else. (This is an

active low-circuit, so active here means low, but for

an active high active would mean high.

12/18/2023 17:20

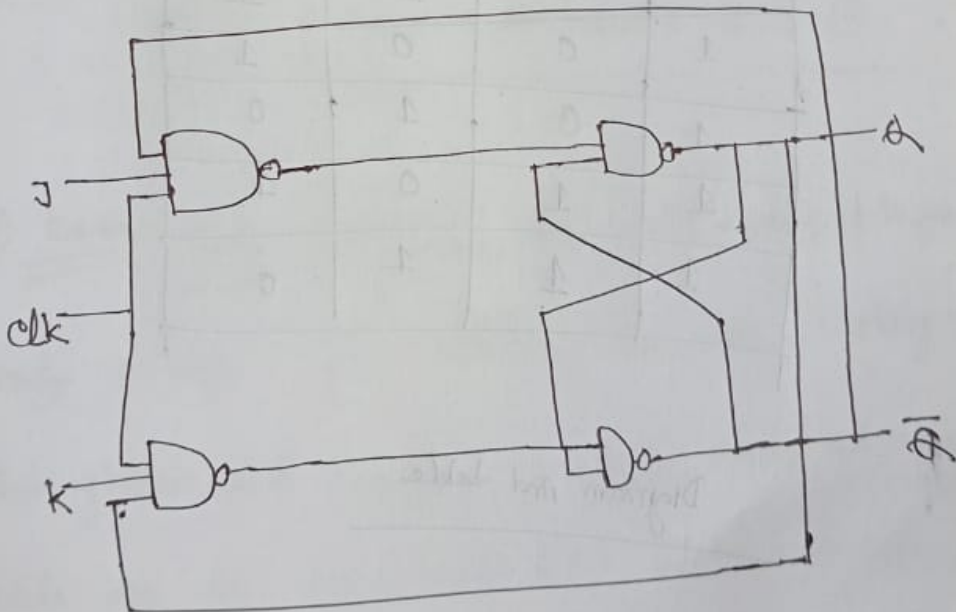
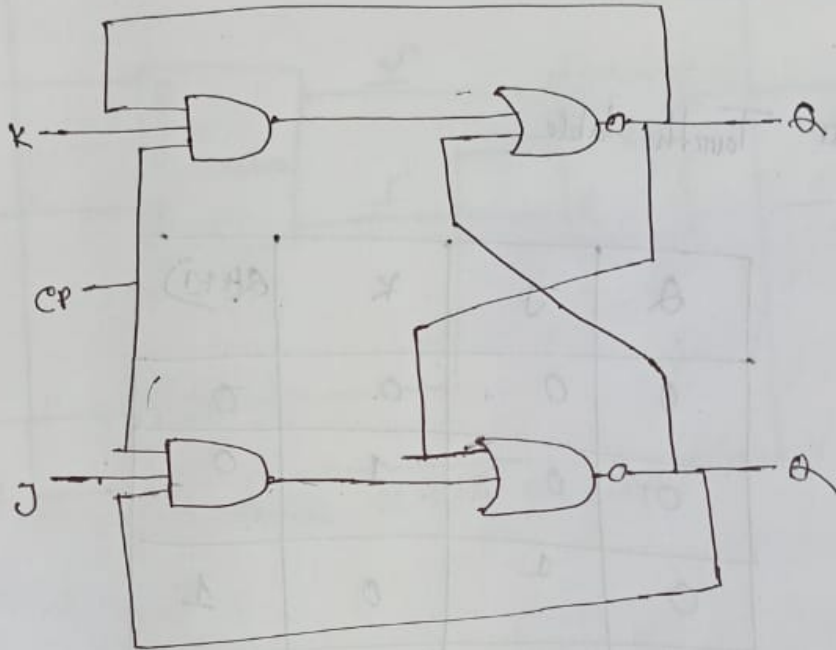
(b) Answer: Types Of Sequential Circuits: There are two types of Sequential Circuits:

Type 1: Asynchronous Sequential Circuit. These Circuits do not use a clock signal but used the pulses of the input. These Circuits are faster than synchronous Sequential Circuits because there is clock pulse and change their state immediately immediately when there is a change in the Output signal. we use asynchronous Sequential Circuits when speed of operation is important and independent of internal clock pulse.

Type-2: Synchronous Sequential Circuit: These Circuits uses clock signal and level input (or pulses) (with restriction on pulse width and circuit propagation). The output pulse is the same duration as the clock pulse for the clocked Sequential Circuits. Since they wait for the next clock pulse to answer to perform the next operation. so these Circuits are bit slower compared to asynchronous. level output change state at the start of an input pulse and remain in that until the next input or clock pulse.

Answer to the Question No-2

① Answer: Controlled Latches using JK flip-flop:



Draw controlled Latches JK.

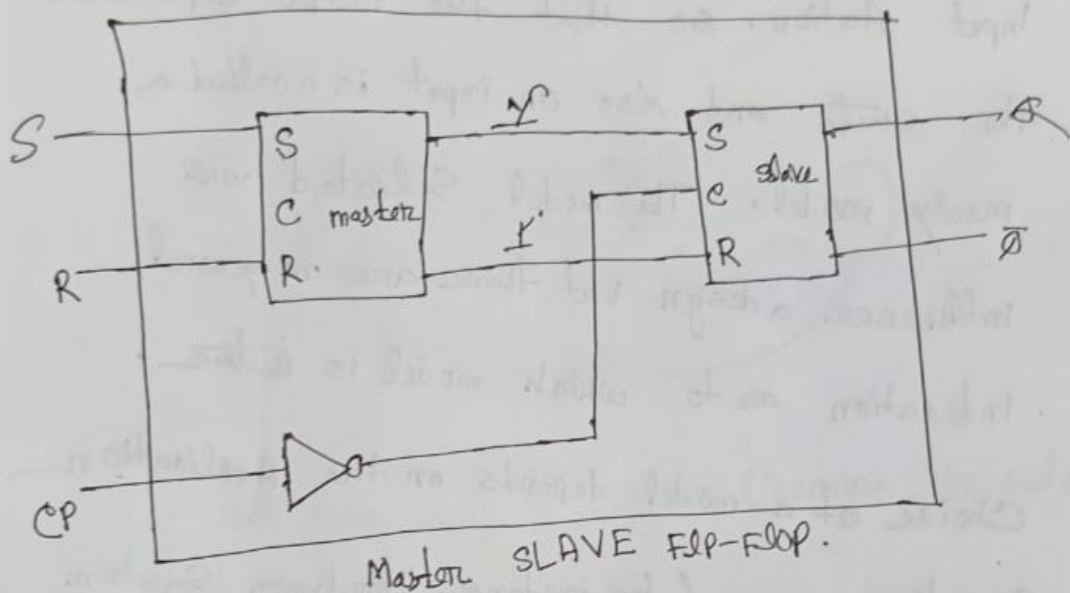
⇒ we can show a characteristics table to show detail about JK latch Here is the characteristic.

III Truth table

A	J	K	Q_{n+1}
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	1
1	0	0	1
1	0	1	0
1	1	0	1
1	1	1	0

Diagram And table

(b) Answer: Draw the master slave SR-flop-flop



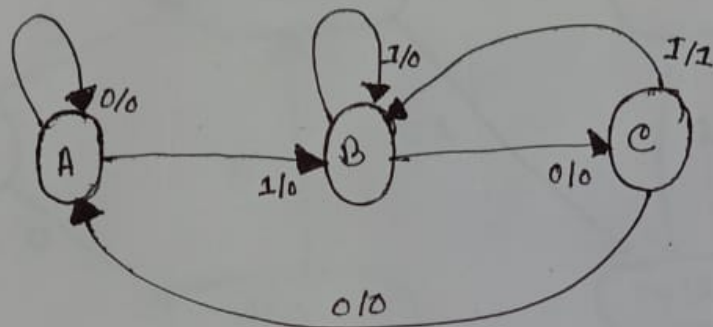
Answer to the Question No - 3 - (a)

(a) Answer: Mealy models/moore: The mealy models it requires only 5 state. The states: Idle, Idle, cooking and Cooking interrupted for that model. mealy and moore models are the basic models of state machines. A state machine which uses only Entry Action, so

that its output depends on the state, is called a Moore model. A state machine which uses only input action, so that the output depends on the state and also on input is called a Mealy model. The model selected will influence a design but there are no general indications as to which model is better.

Choice of a model depends on the application. Execution means (for instance, hardware systems) are usually best realised as Moore models) and personal preference of a designer or programmer. In practice, mixed models are often used with several action types.

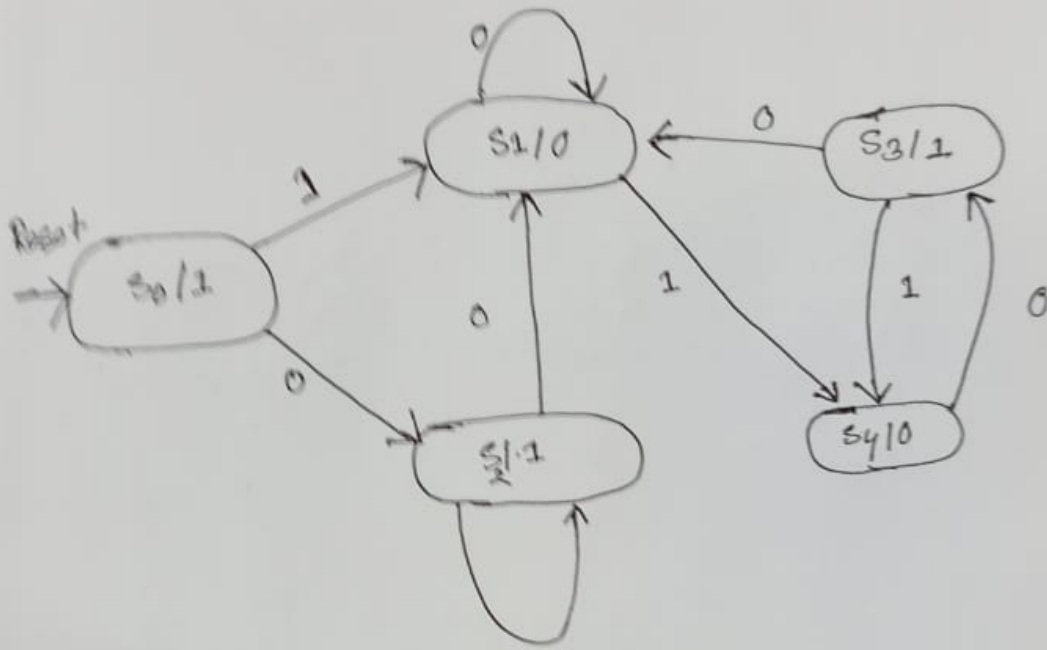
3 (b) Answer: Mealy State machine Diagram.



⇒ Self arcs must be shown (because the output values are shown on the arcs).

⇒ Can be more compact than Moore machine especially when two or more arcs with different output values go into the same state.

(3) (a) Answer: State Diagram moore machine:



(a) provide the state transition table.

(b) Implement the moore FSM using T FFs

(assign the value to the state starting from 0
And adding 1 for each next state 0, 1, 2, ...))

(c) Convert the moore FSM in a mealy style
using state Diagram (you don't have to
implement it, you must show only the
state Diagram.)